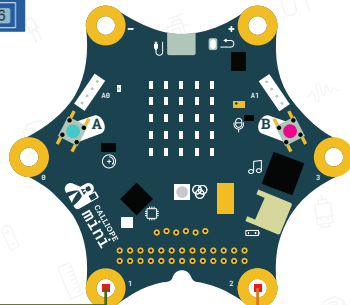


PROGRAMM



ROBOTERKONFIGURATION

Sensor analog

~~Sensor digital~~ Rotationssensor
pin P1

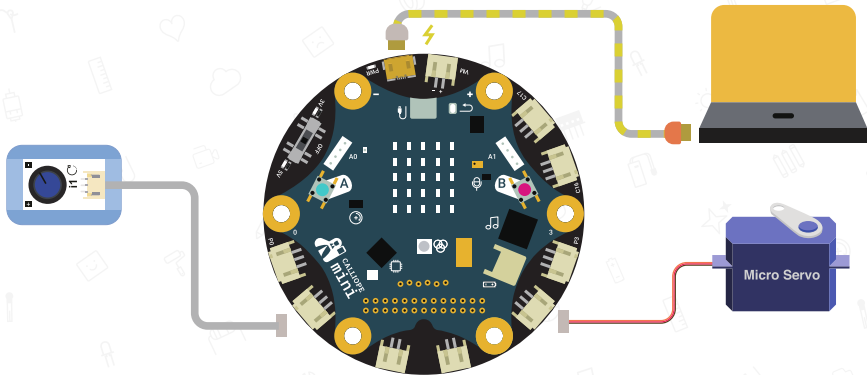
Servomotor

~~Aktor digital~~ Schranke
pin P2



BOSON Projekt 3 - Schranke

VERBINDUNGSDIAGRAMM



DFROBOT
DRIVE THE FUTURE



CALLIOPE