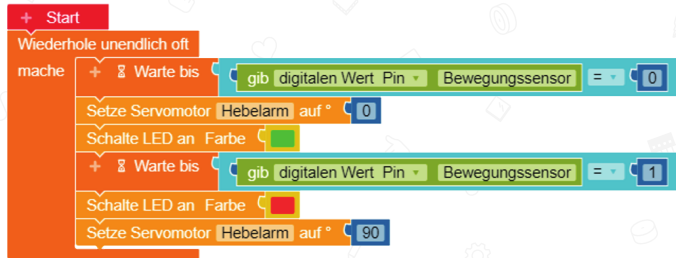


PROGRAMM

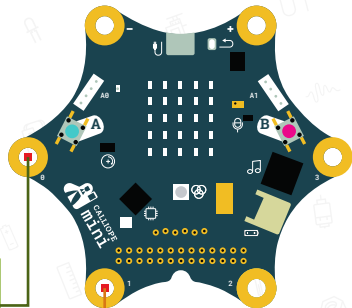


ROBOTERKONFIGURATION

Sensor digital Bewegungssensor
pin P0

Servomotor

~~Aktor digital~~ Hebelarm
pin P1



VERBINDUNGSDIAGRAMM

